Answer Key for Practice Quiz - 1

CS 591Q/791V - Pattern Recogniton Instructor: Dr. Arun Ross Posted on: Mar 8, 2010

1. a. Bayes Risk: [pp. 24-25] Consider the problem of designing a pattern classification system where the goal is to assign a d-dimensional feature vector x to one of c classes, $\omega_1,\dots\omega_c$, resulting in one of a actions, $\alpha_1,\dots\alpha_a$. Denote as $\lambda(a_i|\omega_j)$ the cost of taking action a_i when the true class of the input pattern x is ω_j . Then the conditional risk of taking action α_i upon encountering feature vector \boldsymbol{x} is

$$
R(\alpha_i|\mathbf{x}) = \sum_{j=1}^c \lambda(\alpha_i|\omega_j) P(\omega_j|\mathbf{x}),
$$

for $i = 1, \ldots a$. Thus, the decision policy would be to select that action α_i for which $R(\alpha_i|\mathbf{x})$ is minimum. The resulting minimum overall risk is called the Bayes Risk.

b. Minimum Distance Classifier: [p. 39] Given a feature vector x and a set of mean vectors μ_1, \ldots, μ_c corresponding to *c* classes, $\omega_1, \dots \omega_c$, the minimum distance classifier assigns *x* to that class whose mean vector is located at the smallest Euclidean distance from *x*. Thus,

Assign **x** to class
$$
\omega_{j^*}
$$
, where $j^* = \arg \min_{j=1,\dots,c} ||x - \mu_j||$.

2. [see Figure 2.13 in p. 41 to view a similar problem]

The decision boundary can be computed as:

$$
P(\omega_1|x) = P(\omega_2|x)
$$

\n
$$
\Rightarrow p(x|\omega_1|) = p(x|\omega_2), \quad \text{(since } P(\omega_1) = P(\omega_2) \text{)}
$$

\n
$$
\Rightarrow \frac{1}{\sqrt{2\pi 1}} exp\left(-\frac{1}{2}x^2\right) = \frac{1}{\sqrt{2\pi 4}} exp\left(-\frac{1}{2}\frac{(x-\frac{1}{2})^2}{4}\right)
$$

Applying ln on both sides and multiplying by -1, we have:

$$
\frac{x^2}{2} = \ln 2 + \frac{(x - \frac{1}{2})^2}{8}
$$

\n
$$
\Rightarrow \frac{x^2}{2} = \ln 2 + \frac{1}{8} \left(x^2 - x + \frac{1}{4} \right)
$$

\n
$$
\Rightarrow 4x^2 = 8 \ln 2 + (x^2 - x + \frac{1}{4})
$$

\n
$$
\Rightarrow 3x^2 + x - 5.79 = 0
$$

\n
$$
\Rightarrow x = -1.56 \text{ or } x = 1.23
$$

Thus the decision rule will be,

$$
\begin{cases} x \in \omega_1, & \text{if } -1.56 < x < 1.23, \\ x \in \omega_2, & \text{otherwise.} \end{cases}
$$

3. [see section 2.7]

Note that $\omega_{max}({\bm x})$ denotes the class that ${\bm x}$ is assigned to by the Bayes classifier. It could be one of $\omega_1,\dots\omega_c$ depending on the feature vector *x*. So, $P(correct|\mathbf{x}) = P(\omega_{max}|\mathbf{x})$. Thus,

$$
P(correct|\mathbf{x}) = P(\omega_{max}|\mathbf{x})
$$

\n
$$
\Rightarrow P(correct) = \int P(\omega_{max}|\mathbf{x})p(\mathbf{x})d\mathbf{x}
$$

\n
$$
\Rightarrow P(error) = 1 - \int P(\omega_{max}|\mathbf{x})p(\mathbf{x})d\mathbf{x}.\square
$$

4. [see section 2.5.1]

The entropy of a distribution $p(x)$ is given by

$$
H(p(x)) = -\int p(x) \ln[p(x)] dx,
$$

where the integral is in the interval $[-\infty, \infty]$. In this case,

$$
p(x) = \frac{1}{\sqrt{(2\pi\sigma^2)}}e^{-\frac{x^2}{2\sigma^2}},
$$

and

$$
ln[p(x)] = -ln[\sqrt{(2\pi\sigma^2)}] - \frac{x^2}{2\sigma^2} = - (ln[\sqrt{(2\pi\sigma^2)}] - \frac{x^2}{2\sigma^2}).
$$

Thus,

$$
H(p(x)) = -\int p(x) \ln[p(x)]dx
$$

\n
$$
= \int p(x) (\ln[\sqrt{(2\pi\sigma^2)}] + \frac{x^2}{2\sigma^2})dx
$$

\n
$$
= \int p(x) \ln[\sqrt{(2\pi\sigma^2)}]dx + \int p(x) \frac{x^2}{2\sigma^2}dx
$$

\n
$$
= \ln[\sqrt{(2\pi\sigma^2)}] \int p(x)dx + \frac{1}{2\sigma^2} \int x^2 p(x)dx
$$

\n
$$
= \ln[\sqrt{(2\pi\sigma^2)}] + \frac{1}{2\sigma^2}\sigma^2
$$

\n(since $\int p(x)dx = 1$, and $\int x^2 p(x)dx$ is the formula for the variance of a 0-mean gaussian distribution)
\n
$$
= \ln[\sqrt{(2\pi\sigma^2)}] + \frac{1}{2}
$$

\n
$$
= \ln[\sqrt{(2\pi\sigma^2)}] + \frac{1}{2}\ln(e)
$$

\n
$$
= \ln[\sqrt{(2e\pi\sigma^2)}] \cdot \Box
$$

\n(since $\frac{1}{2} \ln(e) = \ln(\sqrt{e}))$)