

Case-Based Reasoning for Reducing Software Development Effort

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ABSTRACT

How can we best find project changes that most improve project estimates? Prior solutions to this problem required the use of standard software process models that may not be relevant to some new project. Also, those prior solutions suffered from limited verification (the only way to assess the results of those studies was to run the recommendations back through the standard process models).

Combining case-based reasoning and contrast set learning, the \mathcal{W} system requires no underlying model. Hence, it is widely applicable (since there is no need for data to conform to some software process models). Also, \mathcal{W} 's results can be verified (using hold-out sets). For example, in the experiments reported here, \mathcal{W} found changes to projects that greatly reduced estimate median and variance by up to 95% and 83% (respectively).

1. INTRODUCTION

Existing research in effort estimations focuses mostly on deriving estimates from past project data using (e.g.) parametric models [6] or case-based reasoning (CBR) [40] or genetic algorithms [22]. That research is curiously silent on how to change a project in order to (say) reduce development effort. That is, that research reports *what is* and not *what should be changed*.

Previously [12, 26, 28, 31], we have tackled this problem using STAR/NOVA, a suite of AI search algorithms that explored the input space of standard software process models to find project options that most reduced the effort estimates. That approach had some drawbacks including (a) the dependency of the data to be in the format of the standard process models; (b) the implementation complexity of the Monte Carlo simulator and the AI search engines; and (c) the lack of an independent verification module (the only way to assess the results of those studies was to run the recommendations back through the standard process models).

This paper describes " \mathcal{W} ", a simpler, yet more general, solution to the problem of finding project changes that most improves project estimates. Combining case-based reasoning and contrast set learning, \mathcal{W} requires no underlying parametric model. Hence, \mathcal{W} can be applied to more data sets (since there is no requirement for

the data sets to be in the format required by the standard software process models). For example, this paper explores five data sets with \mathcal{W} , three of which cannot be processed using STAR/NOVA.

\mathcal{W} is simpler to implement than STAR/NOVA (hundreds of lines of AWK vs thousands of lines of C++/LISP) and easier to use. For example, we describe below a case study that finds a loophole in Brooks's Law ("adding manpower (sic) to a late project makes it later"). Using \mathcal{W} , that study took three days (which included the time to build \mathcal{W} , from scratch). An analogous study, based on state-of-the-art model-based AI techniques, took two years.

Also, the accuracy of STAR/NOVA is only as good as the underlying model (the USC COCOMO suite [6]). \mathcal{W} 's results, on the other hand, are verified using hold-out sets on real-world data. In the experiments reported below, we show that \mathcal{W} can find changes to projects that greatly reduced estimate median and variance by up to 95% and 83% (respectively).

Finally, the difference between \mathcal{W} (that finds what to change in order to improve an estimate) and a standard case-based effort estimator (that only generates estimates) is very small. Based on the this experiment, we advise augmenting standard CBR tools with modules like planning sub-systems like \mathcal{W} .

The rest of this paper is structured as follows. After some background notes on effort estimation and STAR/NOVA, we describe the general framework for case-based reasoning. The \mathcal{W} extension to CBR is then described (contrast set learning over the local neighborhood), using a small example. This is followed by fourteen case studies (one with Brooks's Law, and thirteen others). Our conclusion will discuss when \mathcal{W} is preferred over STAR/NOVA.

2. BACKGROUND

2.1 Why Study Effort Estimation?

Generating (and regenerating) project effort estimates is an important and continuous process for project managers. Good estimates allow better utilize resources. Also, by reviewing and improving their estimation process, a software company can learn and improve from their past experience.

Sadly, we often get estimates wrong. Consider the NASA's Check-out Launch Control System, which was canceled when the initial estimate of \$200 million was overrun by an *additional* \$200M [42]. This case is not unique, despite the significant effort put into designing more accurate estimation models, it has been reported that many predictions are wrong by a factor of four or more [5, 19].

In order to conduct software effort estimation, it is standard practice to use models to estimate effort. Many software process models have emerged aiming to achieve that task, and there has not emerged a single standardized model that is widely used by the

software engineering industry. There several reasons for this including *generality*, *data islands* and *instability*. Software models may not be *general* so it can be inappropriate to apply a software model learned in environment one to environment two. Also, many companies prefer to keep cost related data confidential. This *data island* effect has also contributed to the fragmentation of the field by preferring building private models rather than using publicly available models. This multiplicity of software effort models has lead to scarcity of the publicly available local data needed for the model based effort estimation. Without sufficient data to build, audit, and tune models, the predictions generated by these models may be highly *unstable*. Baker [4] reports a study that learned values for the (a, b) (linear,exponential) constants in Boehm' CO-COMO software process model [5]. The study was repeated 100 times, each time selecting at a random sample of 90% of the project data. The learned values for (a, b) exhibited an alarming variance:

$$(2.2 \leq a \leq 9.18) \wedge (0.88 \leq b \leq 1.09) \quad (1)$$

Such large variations make it hard to understand the effects of changing project options. Suppose some proposed change doubles productivity, but a moves from 9 to 4.5. The improvement resulting from that change would be obscured by the tuning variance.

2.2 Handling Large Variances and Uncertainty

The process simulation community (e.g. Raffo [37]) studies elaborate software process models. While such models offer a detailed insight into an organization, the effort required to tune them is non-trivial. For example, Raffo spent two years tuning one such model to one particular site [36]. Slow tuning time means that models will exhibit large variances for much of their lifetime.

These large variances defeat standard decision making algorithms. For example, a standard tool in sensitivity analysis [38] is to partially differentiate the equations of a model, then explore the coefficients on the partials. Large variances like Equation 1 guarantee that any such gradient analysis will yield highly variable results.

Miller [33] reports that *feature selection* can reduce model prediction variance. While he was talking specifically about least squares regression, the more general point is that the fewer the variables, the less the contribution of variable variance to output variance. Inspired by Miller, we conducted feature selection experiments with effort data sets [10,24,29], with disappointing results. As predicted by Miller, variance is decreased when (say) 20 attributes are reduced to 10. But note in Baker's study that large variances persist for effort data, even after reducing the number of variables to two. Clearly, we need to look further than just feature selection.

An alternative to feature selection is *case selection* where a data sets of size D are replaced with a smaller data set of *prototypes*. The smaller the data set, the few fewer the values and (hopefully), the smaller the variance. *Prototype generation* should not be confused with nearest neighbor methods: the latter is run on a per-query basis while the former is run once as a pre-processor to all subsequent inferecing. The art of prototype generation is to find or generate, a set of representative examples that best represents and replaces the training cases. Typically, prototype generation removes most of the training data. For example, Chang's prototype generators [8] replaced training sets of size $T = (514, 150, 66)$ with prototypes of size $N = (34, 14, 6)$ (respectively). That is, prototypes may be as few as $\frac{N}{T} = (7, 9, 9)\%$ of the original data. The problem with prototype generation is that it can be very slow. [22] discusses genetic algorithms that combine feature and case selection. Dr. Li was kind enough to share his code. Using that system, we have learned that searching the 2^D space of possible cases can be very slow. A similar result was reported by Kirsopp and

Shepperd [20], who found that case selection was only practical for very small data sets.

If we cannot remove variance, we must deal with the uncertainties it presents. Much of the related work on uncertainty in software engineering uses a Bayesian analysis. For example, Pendharkar et.al. [35] demonstrate the utility of Bayes networks in effort estimation while Fenton and Neil explore Bayes nets and defect prediction [13]. We take a different approach here due to the simplicity of our implementation (see below).

Of all the literature, we found Search-Based Software Engineering (SBSE) [16] to be closest to this work. SBSE uses optimization techniques from operations research and meta-heuristic search (e.g. simulated annealing and genetic algorithms) to hunt for near optimal solutions to complex and over-constrained software engineering problems. The SBSE approach can and has been applied to many problems in software engineering (e.g. requirements engineering [17]) but most often in the field of software testing [3].

2.3 STAR and NOVA

The SBSE literature inspired us try simulated annealing to search the what-ifs associated with Equation 1. This lead to the STAR system [12,28]. NOVA was a generalization of STAR that included simulated annealing, and other search engines [26,31].

STAR/NOVA handled model variance by finding conclusions that were stable across the space of possible tunings. This analysis assumed that, for a mature effort estimation model, the range of possible tunings was known (this is the case for models like COCOMO). For such models, it is possible for the AI search engines to find conclusions that hold across the space of all tunings.

STAR and NOVA constrain project options P but not the tuning options T . Hence, their recommendations contains subsets of the project options P that most improve the score, despite variations in the tunings T . This approach meant we could reuse COCOMO models requiring using local tuning data. The following is a description that briefly presents the operation of STAR and NOVA:

1. *SAMPLE*: We sample across the ranges of all the attributes in the model n_1 times. Most of the time we sample randomly across the range, with some heuristics that allow us to concentrate more on the extremes of the range.
2. *DISCRETIZE*: The data seen in the n_1 samples is then discretized into $D = 10$ bins. Equal frequency bins were used.
3. *CLASSIFY*: The top $n\%$ projects are classified *best* or *rest*.
4. *RANK*: The ranges are then ranked in increasing order using Support-Based Bayesian Ranking.
5. *PRUNE*: STAR runs n_2 experiments with the models where the top ranked ranges $1..X$ ranges are pre-set and the remaining ranges can be selected at random.
6. *REPORT*: STAR returns the $1..X$ settings that optimize the best for the fitness function. These settings are determined by iterating back from the minimum point achieved towards the first point that is statistically similar to the minimum point.

In practice, STAR/NOVA approach was very effective. Figure 1 shows the large effort reductions found by STAR in three out of four case presented at ASE'09. It is insightful to reflect about STAR/NOVA's failure to find large reductions in the fourth case study (*nasa93 osp2*). In this project, management had already fixed most of the project options. STAR/NOVA failed, in this case, since there was very little left to try and change. This fourth case study lead to one of the lessons learned of STAR/NOVA: apply project option exploration tools as early as possible in the lifecycle of a project. Or, to say that more succinctly: *if you fix everything, there is nothing left to fix* [27].

study	NOVA
nasa93 flight	72%
nasa93 ground	73%
nasa93 osp	42%
nasa93 ops2	5%

Figure 1: Improvements in effort estimates ($\frac{initial-final}{initial}$) **found by NOVA. From [14].**

While a successful prototype, STAR/NOVA has certain drawbacks:

- **Model dependency:** STAR/NOVA requires a model to calculate (e.g.) estimated effort. In order to do so, we had to use some software process models to generate the estimates. Hence, the conclusions reached by STAR/NOVA are only as good as this model. That is, if a client doubts the relevance of those models, then the conclusions will also be doubted.
- **Data Dependency:** STAR/NOVA's AI algorithms explored an underlying software process model. Hence, it could only process project data in a format compatible with the underlying model. In practice, this limits the scope of the tool.
- **Inflexibility:** It proved to be trickier than we thought to code up the process models, in a manner suitable for Monte Carlo simulation. By our count, STAR/NOVA's models required 22 design decisions to handle certain special cases¹. Lacking guidance from the literature, we just had to apply "engineering judgement" to make those decisions. While we think we made the right decisions, we cannot rigorously justify them.
- **Performance:** Our stochastic approach conducted several tens of thousands of iterations to explore the search space, with several effort estimates needed calculated for each iteration. This resulted in a performance disadvantage.
- **Size and Maintainability:** Due to all the above factors, our code base proved difficult to maintain.

While there was nothing in principle about applying our techniques to other software effort models, we believe that the limiting factor on disseminating our technique is the complexity of our implementation. As partial evidence for this, we note that in the three years since we first reported our technique [28]:

- We have only coded one set of software process models (CO-COMO), which inherently limited the scope of our study.
- No other research group has applied these techniques.

Therefore, rather than elaborate a complex code base, we now explore a different option, based on Case Based Reasoning (CBR). This new approach had no model restrictions (since it does not use a model) and can accommodate a wide range of data sets (since there are no restrictions of the variables that can be processed).

3. CASE-BASED REASONING (CBR)

Case based reasoning is a method of machine learning that seeks to emulate human recollection and adaptation of past experiences in order to find solutions to current problems. That is, as humans we tend to base our decisions not on complex reductive analysis, but on an instantaneous survey of past experiences [39]; i.e. we don't think, we remember. CBR is purely based on this direct adaptation

¹E.g. one user required the following modification: do not increase automatic tools usage without increasing analyst capability.

of previous cases based on the similarity of those cases with the current situation. Having said that, a CBR based system has no dedicated world model logic, rather that model is expressed through the available past cases in the case cache. This cache is continuously updated and appended with additional cases.

Aamodt & Plaza [1] described a 4-step general CBR cycle, which consisting of:

1. **Retrieve:** Find the most similar cases to the target problem.
2. **Reuse:** Adapt our actions conducted for the past cases to solve the new problem.
3. **Revise:** Revise the proposed solution for the new problem and verifying it against the case base.
4. **Retain:** Retain the parts of current experience in the case base for future problem solving.

Having verified the results from our chosen adapted action on the new case, the new case is added to the available case base. The last step allows CBR to effectively learn from new experiences. In this manner, a CBR system is able to automatically maintain itself. As discussed below, \mathcal{W} supports *retrieve*, *reuse*, *revise* (and *retain* is a decision left up to the user collecting project data).

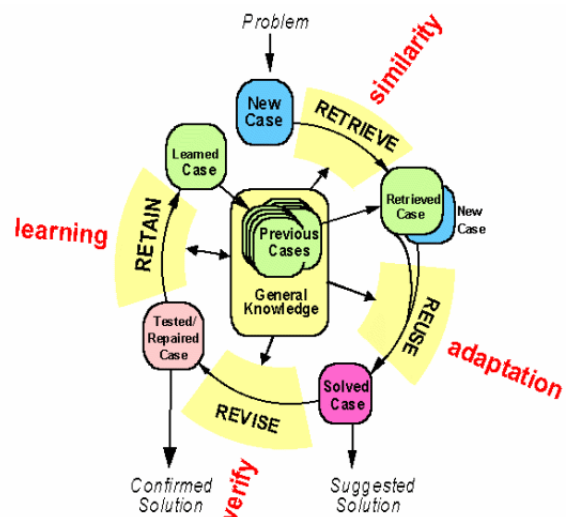


Figure 2: figure

A diagram describing the steps of CBR (source: <http://www.peerscience.com/Assets/cbrcycle1.gif>).

This 4-stage cyclical CBR process is sometimes referred to as the R4 model [41]. Shepperd [41] considered the new problem as a case that comprises two parts. There is a description part and a solution part forming the basic data structure of the system. The description part is normally a vector of features that describe the case state at the point at which the problem is posed. The solution part describes the solution for the specific problem (the problem description part).

The similarity between the target case and each case in the case base is determined by a similarity measure. Different methods of measuring similarity have been proposed for different measurement contexts. A similarity measure is measuring the closeness or the distance between two objects in an n-dimensional Euclidean space, the result is usually presented in a distance matrix (similarity matrix) identifying the similarity among all cases in the dataset. Although there are other different distance metrics available for dif-

ferent purposes, the Euclidean distance metric is probably the most commonly used in CBR for its distance measures.

Irrespective of the similarity measure used, the objective is to rank similar cases from case-base to the target case and utilize the known solution of the nearest k -cases. The value of k in this case has been the subject of debate [18,40]: Shepperd [40], Mendes [23] argue for $k = 3$ while Li [22] propose $k = 5$.

Once the actual value of the target case is available it can be reviewed and retained in the case-base for future reference. Stored cases must be maintained over time to prevent information irrelevancy and inconsistency. This is a typical case of incremental learning in an organization utilizing the techniques of CBR.

Observe that these 4 general CBR application steps (retrieve, reuse, revise, retain) do not include any explicit model based calculations; rather we are relying on our past experience, expressed through the case base, to estimate any model calculations based on the similarity to the cases being used. This has two advantages:

1. It allows us to operate independently of the models being used. For example, our prior report to this conference [14] ran over two data sets. This study, based on CBR, uses twice as many data sets.
2. This improves our performance, since data retrieval can be more efficient than calculation, especially given that many thousands of iterations of calculation were needed with our traditional modeling based tool. As evidence of this, despite the use of a slower language, \mathcal{W} 's AWK code runs faster than the C++/LISP used in STAR/NOVA. It takes just minutes to conduct 20 trials over 13 data sets with \mathcal{W} . A similar trial, conducted with NOVA or STAR, can take hours to run.

4. FROM CBR TO \mathcal{W}

A standard CBR algorithm reports the median class value of some local neighborhood. The \mathcal{W} algorithm treats the local neighborhood in a slightly different manner:

- The local neighborhood is divided into *best* and *rest*;
- A *contrast set* is learned that most separates the regions (contrast sets contain attribute ranges that are common in one region, but rare in the other).
- \mathcal{W} then searches for a subset of the contrast set that best selects for (e.g.) the region with lower effort estimates.

The rest of this section details the above process.

4.1 Finding Contrast Sets

Once a contrast set learner is available, it is a simple matter to add \mathcal{W} to CBR. \mathcal{W} finds contrast sets using a greedy search, where candidate contrast sets are ranked by the log of the odds ratios. Let some attribute range x appear at frequency N_1 and N_2 in two regions of size R_1 and R_2 . Let the R_1 region be the preferred goal and R_2 be some undesired goal. The log of the odds ratio, or LOR, is:

$$LOR(x) = \log \left(\frac{N_1/R_1}{N_2/R_2} \right)$$

Note that when $LOR(x) = 0$, then x occurs with the same probability in each region (such ranges are therefore not useful for selecting on region or another). On the other hand, when $LOR(x) > 0$, then x is more common in the preferred region than otherwise. These LOR-positive ranges are candidate members of the contrast set that selects for the desired outcome.

It turns out that, for many data sets, the LOR values for all the ranges contain a small number of very large values (strong contrasts) and a large number of very small values (weak contrasts).

The reasons for this distribution do not concern us here (and if the reader is interested in this *master-variable* effect, they are referred to [25, 30]). What is relevant is that LOR can be used to rank candidate members of a contrast set. \mathcal{W} computes the LORs for all ranges, then conducts experiments applying the top i -th ranked ranges.

For more on LOR, and their use for multi-dimensional data, see [34].

4.2 The Algorithm

CBR systems input a query q and a set of cases. They return the subset of cases C that is relevant to the query. In the case of \mathcal{W} :

- Each case C_i is an historical record of one software projects, plus the development effort required for that project. Within the case, the project is described by a set of attributes which we assume have been discretized into a small number of discrete values (e.g. analyst capability $\in \{1, 2, 3, 4, 5\}$ denoting very low, low, nominal, high, very high respectively).
- Each query q is a set of constraints describing the particulars of a project. For example, if we were interested in a schedule over-run for a complex, high reliability projects that have only minimal access to tools, then those constraints can be expressed in the syntax of Figure 4.

\mathcal{W} seeks q' (a change to the original query) that finds another set of cases C' such that the median effort values in C' are less than that of C (the cases found by q). \mathcal{W} finds q' by first dividing the data into two-thirds training and one-third testing. *Retrieve* and *reuse* are applied to the training set, then *revising* is applied to the test set.

1. *Retrieve*: The initial query q is used to find the N training cases nearest to q (using a Euclidean distance measure where all the attribute values are normalized 0..1).
2. *Reuse* (adapt): The N cases are sorted by effort and divided into the K_1 best cases (with lowest efforts) and K_2 rest cases. For this study, we used $K_1 = 5, K_2 = 15$. Then we seek the contrast sets that select for the K_1 best cases with lowest estimates. All the attribute ranges that the user has marked as "controllable" are scored and sorted by LOR. This sorted order S defines a set of candidate q' queries that use the first i -th entries in S :

$$q'_i = q \cup S_1 \cup S_2 \dots \cup S_i$$

Formally, the goal of \mathcal{W} is find the smallest i value such q'_i selects cases with the least median estimates.

According to Figure 2, after *retrieving* and *reusing* comes *revising* (this is the "verify" step). When revising q' , \mathcal{W} prunes away irrelevant ranges as follows:

1. Set $i = 0$ and $q'_i = q$
2. Let $Found_i$ be the test cases consistent with q'_i (i.e. that do not contradict any of the attribute ranges in q'_i).
3. Let $Effort_i$ be the median efforts seen in $Found_i$.
4. If $Found$ is too small then terminate (due to over-fitting). After Shepperd [40], we terminated for $|Found| < 3$.
5. If $i > 1$ and $Effort_i < Effort_{i-1}$, then terminate (due to no improvement).
6. Print q'_i and $Effort_i$.
7. Set $i = i + 1$ and $q'_i = q'_{i-1} \cup S_i$
8. Go to step 2.

On termination, \mathcal{W} recommends changing a project according to the set $q' - q$. For example, in Figure 4, if $q' - q$ is *rely* = 3 then this treatment recommends that the best way to reduce the effort this project is to rejecting *rely* = 4 or 5.

Dataset	Attributes	Number of cases	Content	Historical Effort Data					
				Units	Min	Median	Mean	Max	Skewness
coc81	17	63	NASA projects	months	6	98	683	11400	4.4
nasa93	17	93	NASA projects	months	8	252	624	8211	4.2
desharnais	12	81	Canadian software projects	hours	546	3647	5046	23940	2.0
maxwell	26	62	Finish banking software	months	6	5189	8223	63694	3.3
isbsg	14	29	Banking projects of ISBSG	minutes	662	2355	5357	36046	2.6
Total: 328									

Figure 3: The 328 projects used in this study come from 5 data sets.

One useful feature of the above loop is that it is not a black box that offers a single “all-or-nothing” solution. Rather it generates enough information for a user to make their own cost-benefit trade offs. In practice, users may not accept all the treatments found by this loop. Rather, for pragmatic reasons, they may only adopt the first few S_i changes seen in the first few rounds of this loop. Users might adopt this strategy if (e.g.) they have limited management control of a project (in which case, they may decide to apply just the most influential S_i decisions).

Implementing \mathcal{W} is simpler than the STAR/NOVA approach:

- Both NOVA and STAR contain a set process models for predicting effort, defects, and project threats as well as Monte Carlo routines to randomly select values from known ranges. STAR and NOVA implement simulated annealing while NOVA also implements other search algorithms such as ASTAR, LDS, MAXWALKSAT, beam search, etc. STAR/NOVA are 3000 and 5000 lines of C++ and LISP, respectively.
- \mathcal{W} , on the other hand, is 300 lines of AWK script

Our pre-experimental suspicion was that \mathcal{W} was too simple and would need extensive enhancement. However, the results shown below suggest that, at least for this task, simplicity can suffice (but see the future work section for planned extensions).

Note that \mathcal{W} verification results are more rigorous than those of STAR/NOVA. \mathcal{W} reports results on data that is external to its deliberation process (i.e. on the test set). STAR/NOVA, on the other hand, only reported the changes to model output once certain new constraints were added to the model input space.

5. DATA

Recall that a CBR system takes input a query q and cases C . \mathcal{W} has been tested using multiple queries on the data sets of Figure 3. These queries and data sets are described below.

5.1 Data Sets

As shown in Figure 3, our data includes:

- The standard public domain COCOMO data set (Cocoma81);
- Data from NASA;
- Data from the International Software Benchmarking Standards Group (ISBSG);
- The Desharnais and Maxwell data sets;

Except for ISBSG, all the data used in this study is available at <http://promisedata.org/data> or from the authors.

Note the skew of this data (min to median much smaller than median to max). Such asymmetric distributions complicate model-based methods that use Gaussian approximations to variables.

There is also much divergence in the attributes used in our data:

- While our data include effort values (measured in terms of months or hours), no other feature is shared by all data sets.

```
@project example
@attribute ?rely 3 4 5
@attribute tool 2
@attribute cplx 4 5 6
@attribute ?time 4 5 6
```

Figure 4: \mathcal{W} 's syntax for describing the input query q . Here, all the values run 1 to 6. $4 \leq cplx \leq 6$ denotes projects with above average complexity. Question marks denote what can be controlled- in this case, *rely*, *time* (required reliability and development time)

- The Cocomo and NASA data sets all use the attributes defined by Boehm [5]; e.g. analyst capability, required software reliability, memory constraints, and use of software tools.
- The other data sets use a variety of attributes such as the number of data model entities, the number of basic logical transactions, and number of distinct business units serviced.

This attribute divergence is a significant problem for model-based methods like STAR/NOVA since those systems can only accept data that conforms to the space of attributes supported by their model. For example, this study uses the five data sets listed in Figure 4. STAR/NOVA can only process two of them (coc81 and nasa93).

CBR tools like \mathcal{W} , on the other hand, avoid these two problems:

- \mathcal{W} makes no assumption about the distributions of the variables.
- \mathcal{W} can be easily applied to any attribute space (caveat: as long but there are some dependent variables).

5.2 Queries

Figure 4 showed an example of the \mathcal{W} query language:

- The idiom “@attribute name range” defines the range of interest for some attribute “name”.
- If “range” contains multiple values, then this represents a disjunction of possibilities.
- If “range” contains one value, then this represents a fixed decision that cannot be changed.
- The idiom “?x” denotes a controllable attribute (and \mathcal{W} only generates contrast sets from these controllables). Note that the “range”s defined for “?x” must contain more than one value, otherwise there is no point to making this controllable.

6. EXAMPLE

Figure 5 shows \mathcal{W} running on the (dataset,query) of (coc81,osp). The osp query comes from our contacts at the Jet Propulsion Laboratory and describes the constraints that apply to the flight guidance system of the Orbital Space plane (see Figure 6).

The **training results** are shown on lines 5 to 8. These are the S_i scores on all the ranges with a positive LOR. Note that one

```

1 historical data : coc81
2 new project(s) : osp
3   #n score range
4 -----
5   1  0.41 stor = 3
6   2  0.09 acap = 5
7   3  0.00 cplx = 4
8
9  q_0:
10 9 15 40 41 50 55 61 79 83 240 387
11 423 523 539 605 702 1063 1600 2040 6400
12
13           25% 50%   75%
14 Baseline:   52.5 313.5 653.5
15
16 Results of applying the top n-th ranges
17 found during training
18
19 q_1: stor=3 : {15 50 55 240 702} (median,spread)= 55,190

```

Figure 5: Running (coc81,osp).

```

@project osp
@attribute data 3
@attribute rely 5
@attribute ?team 2 3
@attribute pcap 3
@attribute ?stor 3 4 5
@attribute ?acap 2 3
@attribute ?aexp 2 3
@attribute ?tool 2 3
@attribute ?sced 1 2 3
@attribute ?cplx 5 6
@attribute kloc 75 80 90 95 100 105 110 115 120 125

```

Figure 6: The *osp* query query says, in part, that system size is between 75 and 125 *kloc*; that required reliability *rely* is very high; but analyst capability *acap* is only fair to medium. For a full description of this query, see [28].

range has an outstandingly high LOR; *stor* = 3 has an LOR of 0.41 while all the rest are under 0.1. That is, we should expect most of the benefit from applying just one range (*stor* = 3).

The **baseline effort estimates** of q_0 are on lines 10,11. These are all the efforts of all the cases selected by the *osp* query. These efforts are summarized on lines 13,14 (the median effort is 313.5).

The **testing results** are after line 18. In this example, q_1 is q_0 (*osp*) plus the top-ranked attribute range (*stor* = 3). The effects of q_1 are on lines 19. Now, only five cases are selected with a median effort of 55. Testing stops at line 19 since applying the next ranges did not improve the median or spread results.

As to performance measures, if $Improvement = \frac{initial-final}{initial}$, then the *median improvement* of Figure 5 is $\frac{313-55}{313} = 82\%$. Also, let the *spread* be the 75th – 25th percentile interval (a non-parametric measure of estimate variance). The spreads of Figure 5 are, for q_0 , $653 - 52 = 601$ and, for q_1 , $240 - 50 = 190$. Hence, the *spread improvement* was $\frac{601-190}{601} = 68\%$. Reducing *both* median and spread are useful since the former relates to development cost and the latter relates to how much we can trust and estimate (the smaller the spread, the more we can trust it).

7. CASE STUDIES

7.1 Case Study #1: Brooks’s Law

This section applies \mathcal{W} to Brooks’s Law. Writing in the 1970s [7], Brooks noted that software production is a very human-centric activity and managers need to be aware of the human factors that increase/decrease productivity. For example, a common practice

```

@project brooks
@attribute ?prec 1 2 3 4 5 6
@attribute ?flex 1 2 3 4 5
@attribute ?resl 1 2 3 4 5
@attribute ?team 1 2 3 4 5
@attribute ?pmat 1 2 3 4 5
@attribute ?rely 1 2 3 4 5
@attribute ?data 2 3 4 5
@attribute ?cplx 1 2 3 4 5 6
@attribute ?ruse 2 3 4 5 6
@attribute ?docu 1 2 3 4 5
@attribute ?time 3 4 5 6
@attribute ?stor 3 4 5 6
@attribute ?pvol 2 3 4 5
@attribute ?acap 1 2 3 4 5
@attribute ?pcap 1 2 3 4 5
@attribute ?pcon 1 2 3 4 5
@attribute apex 1
@attribute plex 1
@attribute ltex 1
@attribute ?tool 1 2 3 4 5
@attribute ?site 1 2 3 4 5 6
@attribute ?sced 1 2 3 4 5
@attribute kloc 0.9 2.2 3 [snip] 339 350 352 423 980

```

Figure 7: The *brookslaw* query.

at that time at IBM was to solve deadline problems by allocating more resources. In the case of programming, this means adding more programmers to the team. Brooks argued that this was an inappropriate response since, according to Brooks’s law “adding manpower (sic) to a late software project makes it later”. The reason for this slowdown is two-fold:

- The more people involved the greater the communication overhead. While this is certainly an issue if all parts of the software system are accessible to all other parts, with an intelligent module design, this first issue can be mitigated.
- The second issue is more fundamental. Software construction is a complex activity. Newcomers to a project suffer from inexperience in the tools, the platform, the problem domain, etc.

The query of Figure 7 models this second issue. In this query, all the experience attributes have been set to their lowest value (*apex*, *plex*, *ltex* are analyst experience, programmer language experience, and language and tool experience, respectively). The remaining attributes are all controllable (as denoted by the “?” in front of each one) and are allowed to move over their full range.

For a (dataset,query) of (nasa93, $q = brookslaw$), \mathcal{W} returns

$$q' = q \cup (data = 2)$$

That is, \mathcal{W} is recommending setting the database size to its lowest value. Databases are used to store program and data elements. In effect, \mathcal{W} is recommending reigning in the scope of the project. The recommendation can be paraphrased as follows:

If the project is late, and you add more staff with less experience, you can still finish on time if you decrease the scope of the project.

Figure 8 shows the effects of this recommendation. The *AsIs* row shows the median and spread of the effort values in nasa93. The *ToBe1* row shows the effect of Brooks’s Law. In the subset of the data consistent with $aexp = plex = ltex = 1$, the median effort has nearly doubles. The *ToBe2* row shows the impact of \mathcal{W} ’s recommendation: the project will now finish in nearly the the time as the *AsIs* row, and the spread is greatly reduced.

One of the reasons we are exploring \mathcal{W} is simplicity of the implementation. In this regard, it is useful to compare our results

Treatment	median	spread
AsIs = Nasa93	225	670
ToBe1 = $nasa93 \cup q$	380	680
ToBe2 = $nasa93 \cup q'$	220	290

Figure 8: Effort estimates seen in different treatments for the Brooks’ Law Experiment.

```
@project desharnais-team-m
@attribute ?TeamExp -1 0 1
@attribute ?ManagerExp 3 4 5 7
@attribute PointsAjust 302 397 697
```

Figure 9: The *desharnais-team-m* query selects for medium sized projects being developed by teams with low experience.

on Brooks’s Law to other researchers. Brooks’s Law is a well-researched effect and other researchers have found special cases where the general law does not hold. For example, using sophisticated qualitative reasoning techniques, Zhang et al. [44] found their own loopholes in Brooks’s Law. One of us (Keung) worked on site with the Zhang team and reports that the Brooks analysis was the main result of a two year masters graduate thesis. In contrast, writing \mathcal{W} took three days and the specific analysis of Brooks’s Law took twenty minutes from first posing the question, to graphing the output.

7.2 Thirteen More Case Studies

Apart from the Brooks’ Law experiment, we have tested \mathcal{W} on thirteen other case studies:

- For the ISBSG data set, we used our recent experience to describe the constraints suitable for a stand-alone or client server system (denoted *stdalone* and *clientsrv*).
- For the Desharnais data set, we posed queries representing:
 - (s, m, l) denotes (small, medium, large) projects;
 - $(mng, team)$ denotes (manager, team) experience being low.

For example, Figure 9 shows the Desharnais-team-m query.

- For the Cocomo and NASA data sets, we used our contacts at the Jet Propulsion Laboratory to write queries describing (a) *osp* (see above); (b) the second version of that system called *osp2*; as well as (c) generic *flight* and (d) *ground* systems.
- Lacking direct experience with the Finnish financial system, we could not pose specific queries to the Maxwell dataset. Instead, we made half the attributes controllable and used that for the Maxwell query (see Figure 10).

Figure 11 shows the improvements seen in our 13 queries, running on the data sets of Figure 3. As shown by the last line of Figure 11, the usual improvements where (36,68) for (median,spread). Note that, unlike STAR/NOVA, these are results on real-world data sets not used during training.

Figure 12 displays the Figure 11 results graphically. The dashed line indicates the median of the improvements for each axis. One data set had consistently worse results than any other. The gray cells of Figure 11 indicate when \mathcal{W} failed (i.e. where the treatments increased median development effort or spread, or both). Note that the gray cells are found only in the Desharnais results.

On investigation, the root cause of the problem was the granularity of the data. Whereas (e.g.) coc81 assigns only one of six values to each attribute, Desharnais’s attributes had a very wide range.

```
@project maxwell
@attribute ?T01 1 2 3 4 5
@attribute ?T02 1 2 3 4 5
@attribute ?T03 2 3 4 5
@attribute ?T04 2 3 4 5
@attribute ?T05 1 2 3 4 5
@attribute ?T06 1 2 3 4
@attribute ?T07 1 2 3 4 5
@attribute ?T08 2 3 4 5
@attribute ?T09 2 3 4 5
@attribute ?T10 2 3 4 5
@attribute ?T11 2 3 4 5
@attribute ?T12 2 3 4 5
@attribute ?T13 1 2 3 4 5
@attribute ?T14 1 2 3 4 5
@attribute ?T15 1 2 3 4 5
```

Figure 10: The *maxwell* query.

dataset	query q	Improvement	
		median	spread
coc81	ground	95%	83%
coc81	osp	82%	68%
nasa93	ground	77%	15%
ISBSG	stdalone	69%	100%
nasa93	flight	61%	73%
nasa93	osp	49%	48%
maxwell		44%	76%
ISBSG	clientsrv	42%	88%
desharnais	mng-l	36%	-45%
coc81	osp2	31%	71%
nasa93	osp2	27%	42%
desharnais	mng-s	23%	85%
desharnais	mng-m	23%	85%
coc81	flight	0%	18%
desharnais	team-m	0%	60%
desharnais	team-s	-11%	-206%
desharnais	team-l	-15%	-93%
	median	36%	68%

Figure 11: Improvements ($100 * \frac{initial-final}{initial}$) for 13 queries. Sorted by median improvement. Gray cells show negative improvements.

Currently, we are exploring discretization policies to [11, 43] reduce attributes with large cardinality to a smaller set. Tentatively, we can say that discretization solves the problem with Desharnais but we are still studying this aspect of our system.

Even counting the negative Desharnais results, in the majority of cases \mathcal{W} found treatments that improved both the median and spread of the effort estimates. Sometimes, the improvements were modest: in the case of (coc81,flight), the median did not improve (but did not get worse) while the spread was only reduced by 18%. But sometimes the improvements are quite dramatic.

- In the case of (ISBSG, stdalone), a 100% improvement in spread was seen when q' selected a group of projects that were co-developed and, hence, all had the same development time.
- In the case of (coc81, ground), a 95% effort improvement was seen when q' found that ground systems divide into two groups (the very expensive, and the very simple). In this case \mathcal{W} found the factor that drove a ground system into the very simple case.

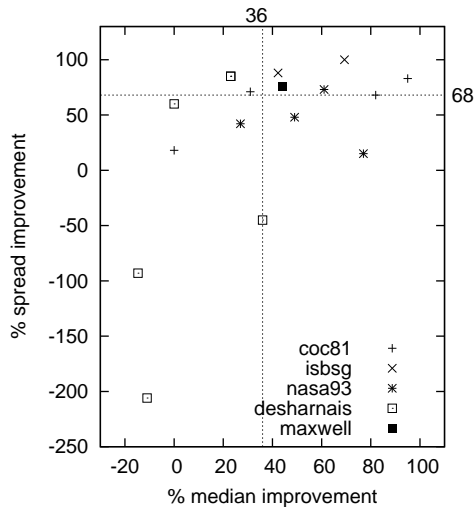


Figure 12: Median and spread improvements for effort estimation. Dashed lines mark the median values of both axes.

8. DISCUSSION

8.1 Comparisons to NOVA

Figure 13 shows that estimation improvements found by \mathcal{W} (in this report) to the improvements reported previously (in Figure 1). This table is much shorter than Figure 11 since, due to the modeling restrictions imposed by the software process models, OVA cannot be applied to all the data sets that can be processed by \mathcal{W} . The numbers in Figure 13 cannot be directly compared due to the different the different goals of the two systems: \mathcal{W} tries to minimize effort while NOVA tries to minimize effort *and* development time *and* delivered defects (we are currently extending \mathcal{W} to handle such multiple-goal optimization tasks). Nevertheless, it is encouraging to note that the results are similar and that the \mathcal{W} improvements are not always less than those found by STAR/NOVA.

study	NOVA	\mathcal{W}
nasa93 flight	72%	61%
nasa93 ground	73%	77%
nasa93 osp	42%	49%
nasa93 ops2	5%	27%

Figure 13: Comparing improvements ($\frac{\text{initial}-\text{final}}{\text{initial}}$) found by NOVA (from Figure 1) and \mathcal{W} (Figure 11).

8.2 Threats to Validity

External validity is the ability to generalize results outside the specifications of that study [32]. To ensure the generalizability of our results, we studied a large number of projects. Our datasets contain a wide diversity of projects in terms of their sources, their domains and the time period they were developed in. Our reading of the literature is that this study uses more project data, from more sources, than numerous other papers. Table 4 of [21] list the total number of projects in all data sets used by other studies. The median value of that sample is 186, which is less much less than the 328 projects used in our study.

Internal validity questions to what extent the cause-effect relationship between dependent and independent variables hold [2].

id	features	relative weight
1	Personnel/team capability	3.53
2	Product complexity	2.38
3	Time constraint	1.63
4	Required software reliability	1.54
5	Multi-site development	1.53
6	Doc. match to life cycle	1.52
7	Personnel continuity	1.51
8	Applications experience	1.51
9	Use of software tools	1.50
10	Platform volatility	1.49
11	Storage constraint	1.46
12	Process maturity	1.43
13	Language & tools experience	1.43
14	Required dev. schedule	1.43
15	Data base size	1.42
16	Platform experience	1.40
17	Arch. & risk resolution	1.39
18	Precedentedness	1.33
19	Developed for reuse	1.31
20	Team cohesion	1.29
21	Development mode	1.32
22	Development flexibility	1.26

Figure 14: Relative effects on development effort. Data from a regression analysis of 161 projects. From [6].

For example, the above results showed reductions in the effort estimates of up to 95%; i.e. by a factor of 20. Are such massive reductions possible?

As shown in Figure 14, these reductions are theoretically possible. Figure 14 shows the relative effects of different factors seen in 161 projects. According to this chart, making maximal changes to the first factor (personnel/team capability) can effect the development effort by up to a 3.53. Making maximal changes just to the first four factors could have a net effect of up to

$$3.53 * 2.38 * 1.62 * 1.54 \approx 21 > 20$$

By the same reasoning, making maximal changes to all factors could have a net effect of up to eleven thousand. Hence, an improvement of 95% (or even more) is theoretically possible.

As to what is pragmatically possible, that is a matter for human decision making. No automatic tool such as STAR/NOVA/ \mathcal{W} has access to all the personnel factors and organizational constraints known to a human manager. Also, some projects are inherently expensive (e.g. the flight guidance system of a manned spacecraft) and cutting costs by (say) reducing the required reliability of the code is clearly not appropriate. Tools like \mathcal{W} are useful for uncovering options that a human manager might have missed, ultimately the actual project changes must be a human decision.

9. CONCLUSION

If a manager is given an estimate for developing some software, they may ask “how do I change that?”. The model variance problem makes it difficult to answer this question. STAR/NOVA offers one solution to this problem, but those tools required an underlying process model. We have shown here that a case-based reasoning approach (augmented with a simple linear-time greedy search for contrast sets) is simpler to implement and, in the case of Brooks’s Law study, easier to apply than model-based methods.

Since this new method has no model-based assumptions, it can be applied to more data sets. When tested on 13 real-world case studies, this approach found changes to projects that could greatly reduce the median and variance of the effort estimate.

This paper has presented \mathcal{W} in the context of effort estimation. We suspect, but cannot yet show, that the algorithm would be a useful decision aid in many other domains.

Our research has now produced two different methods for finding changes that most effect a project. Both methods search for changes that most effect (and improve) the output effort estimates. \mathcal{W} is a *case-based* method that searches relevant historical examples. On the other hand, STAR/NOVA [14] are *model-based* methods that applies AI search to the input space of software process models.

While we prefer \mathcal{W} to STAR/NOVA (due to the simplicity of the analysis), there are clear indicators of when we would prefer STAR/NOVA over \mathcal{W} . \mathcal{W} is a case-based method. If historical cases are not available, then STAR/NOVA is the preferred method. On the other hand, STAR/NOVA is based on the USC COCOMO suite of models. If the local business users do not endorse that mode, then \mathcal{W} is the preferred method.

10. FUTURE WORK

While a promising prototype, there are many design options left to explore within \mathcal{W} . For example, Equation 2 is a generalization of the Euclidean distance measure used in \mathcal{W} 's training phase:

$$Distance = \sqrt{\sum_{i=1}^n w_i (x_i - y_i)^2} \quad (2)$$

In the above, w_i is a weighting applied to each attribute. Currently, \mathcal{W} uses $w_i = 1$ but there are any number of proven and fast feature weighting schemes that can focus the inferencing away from noisy attributes [9, 15].

Also, there a few too many *magic numbers* within the current version of \mathcal{W} . For example, during training, the best and rest sets are of size $K_1 = 5$ and $K_2 = 15$. Now that we have baseline results, it would be prudent to conduct experiments to see if there are better values for K_1 and K_2 .

One issue is \mathcal{W} 's greedy linear-time search to explore the contrast set. Perhaps some of STAR/NOVA's search algorithms could be applied to \mathcal{W} to improve that aspect of the inference.

Finally, given the power of contrast sets to extract relevant attributes, future work exists in seeing if \mathcal{W} is a useful feature subset selector for other domains.

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