

Using Simulation to Investigate Requirements Prioritization Strategies

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Manifesto for Agile Software Development

We are uncovering better ways of developing software by doing it and helping others do it. Through this work we have come to value:

- Individuals and interactions over processes and tools
- Working software over comprehensive documentation
- Customer collaboration over contract negotiation

Responding to change over following a plan

AG: agile-based

PB: plan-based

That is, while there is value in the items on the right, we value the items on the left more.

- | | | |
|-------------------|----------------|------------------|
| Kent Beck | James Grenning | Robert C. Martin |
| Mike Beedle | Jim Highsmith | Steve Mellor |
| Arie van Bennekum | Andrew Hunt | Ken Schwaber |
| Alistair Cockburn | Ron Jeffries | Jeff Sutherland |
| Ward Cunningham | Jon Kern | Dave Thomas |
| Martin Fowler | Brian Marick | |

This paper

- Specifically:
 - With very little machinery, we can characterize:
 - when PB (plan-based) is better/worse than AG (agile)
 - If PB or AG or XYZ is appropriate for your particular project
- More generally:
 - Our simulator is so very, very, very simple.
 - So, why...
 - Years of grand-standing about polar extremes?
 - Don't we see more automated process debates?

Related work

- COCOMO [Boehm'81&00]: hard-wired into 2 dozen variables
 - What about the concepts not mentioned in COCOMO?
- Search-based SE approach [Harmon'04].
 - optimization techniques from operations research and meta-heuristic search (simulated annealing and genetic algorithms)
 - Seeks near-optimal solutions to:
 - complex over-constrained SE models
 - Or simpler COCOMO-based models (Menzies et.al [ASE'07])
 - SBSE too complex for this requirements study
- Elaborate process simulations (e.g. [Raffo])
 - detailed insight into an organization
 - Hard to tune (e.g. Raffo's Ph.D. model, 2 years tuning effort)
 - Raffo: one large model for all questions
 - Our approach: one very small model per question

Model(λ , σ)

- λ =requirements discovery: rate of new requirements
 - Requirements += Poisson(λ)
- σ =requirements volatility: rate of requirements changing value
 - Value += max(0, value + N(0, σ))
- Steps though $2 \leq I \leq 6$ iterations of requirements review
 - B= base requirements at iteration one (max=25)
 - Early stopping probability of $1/(\max I^{0.33}) = 55\%$
 - Requirements unimplemented at each phase: 20%
- Requirements
 - Value R_x : min_value(30) ... max_value(500)
 - Cost R_x : min_cost(1) ... max_cost(100)
 - Assumed to be nonvolatile

End development time is unknown

Cao, Ramesh, IEEE software 2008

Experiments with volatile costs not insightful

No inter-requirement dependencies

Two kinds of “iterations”

- Project iterations
 - Every so often, pause to consider what to do next
 - At each at pause, deliver Version1, version2, version3,....
- Value iterations
 - Every so often, the value of our requirements change.
 - Assume that after \$N
 - There is a pause, and the value of each requirement is reassigned.
 - $\$N = (\text{total cost of base reqs}) / \text{num_iters}$
- For three of our simulations (AG, AG2, hybrid)
 - One value iteration for each project iteration
- For conventional plan-based prioritization
 - Only one project iteration
 - But numerous value iterations

Agile Prioritization (AG)

- Requirements are prioritized at the beginning of each iteration
 - Requirements are retired, highest value first
- Many, but not all, requirements discovered at first iteration
 - Selected randomly $B = 30\% \leq 40 * N(0,1) \leq 70\%$
- Initialization
 - R= Determine num_req
 - B = number “base requirements” (those known in iteration 1)
 - AG_heap = {1,2,.....,B, B+1 ,...R}
 - AG_plan = {1,2,.....,B}
- Simulation. For each project iteration:
 - Sort AG_plan on value, implement top 80%
 - AG_plan= remaining 20% of AG_plan + Poiss(λ) items of AG_heap

CAO, Ramesh,
IEEE software
2008

- A local search, so prone to local maxima
- Ignores cost

AG2

- Same as AG
 - But sort on value / cost

Hybrid Prioritization (HY)

- Same as AG2 but....
- Sort AG_plan by value/cost,
 - Prune those with value/cost $< \alpha$
 - $\alpha = (\sum \text{remaining values}) / (\sum \text{remaining costs})$

- *HY is a local search, prone to local maxima*
- *But α limits our exploration of dead-ends*

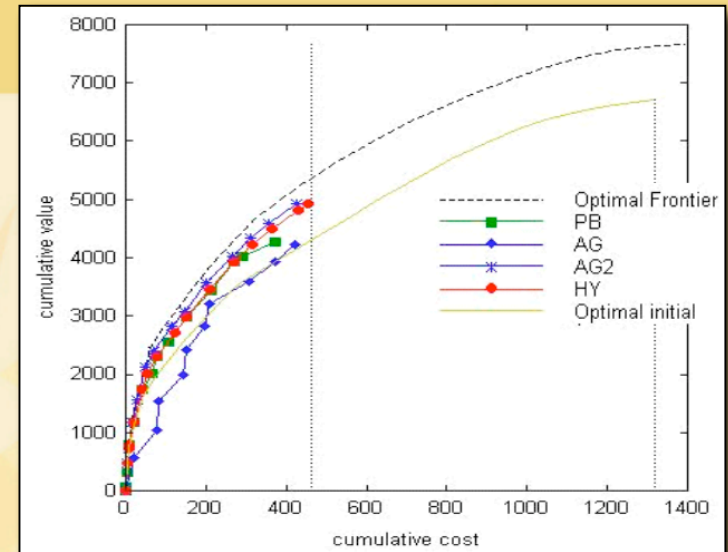
Plan-based Prioritization (PB)

- Requirements are prioritized before iteration 1
 - Using_highest (value/cost)
- Initialization
 - R= Determine num_req
 - B = number “base requirements” (those known in iteration 1)
 - heap = {1,2,...,B, B+1, ...R} sorted by (value/cost)
 - plan = heap
- Simulation:
 - Run down entire plan, left to right
 - Pause every value iteration to adjust requirements value

*See
reference
6, 11*

*• PB is a one-time global search
• Ignores any changes due to
value volatility*

Performance measures

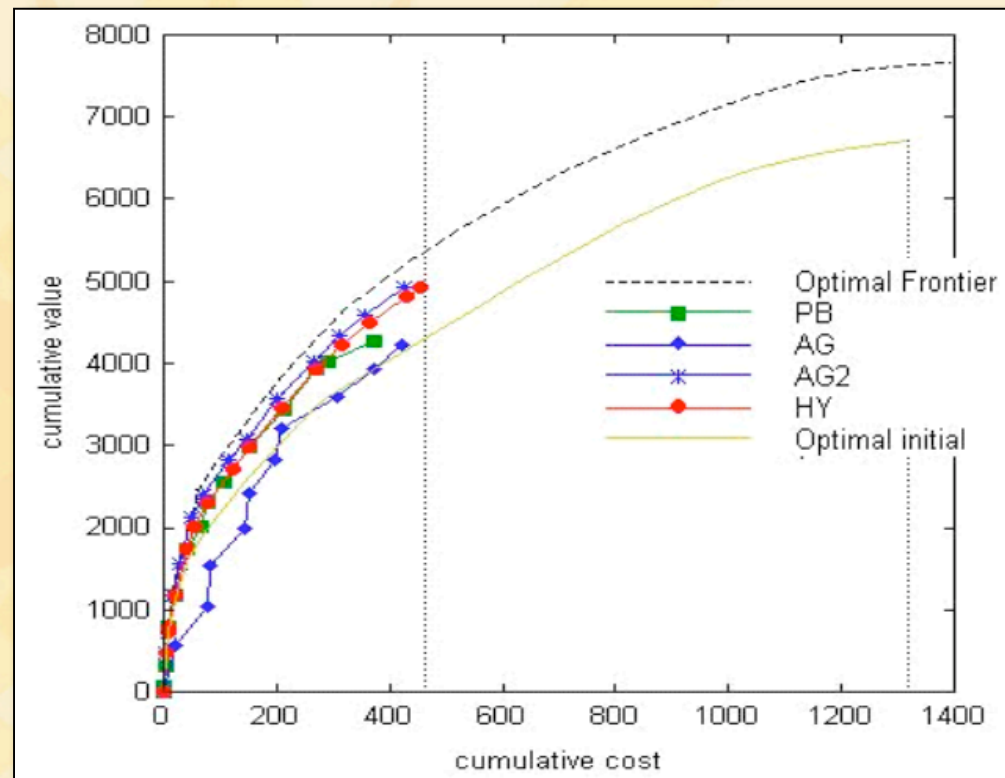


medium dynamism
 $\lambda = 1.4, \sigma = 15\%$

- Control parameters
 - median new requirements discovered per iteration: $0.001 \leq \lambda \leq 20$
 - Requirements value volatility: $0.1\% \leq \sigma \leq 200\%$
- Cumulative
 - Of = Optimal frontier- “after the fact” of ordering of all requirements
 - Note: uses more information that available at any particular iteration
 - Represents maximum possible value.
 - Oi= Optimal initial: ordering the requirements using the initial values
 - Dynamism = Of - Oi (low if initial ordering is best requirements prioritization)

One trial results (1 of 3)

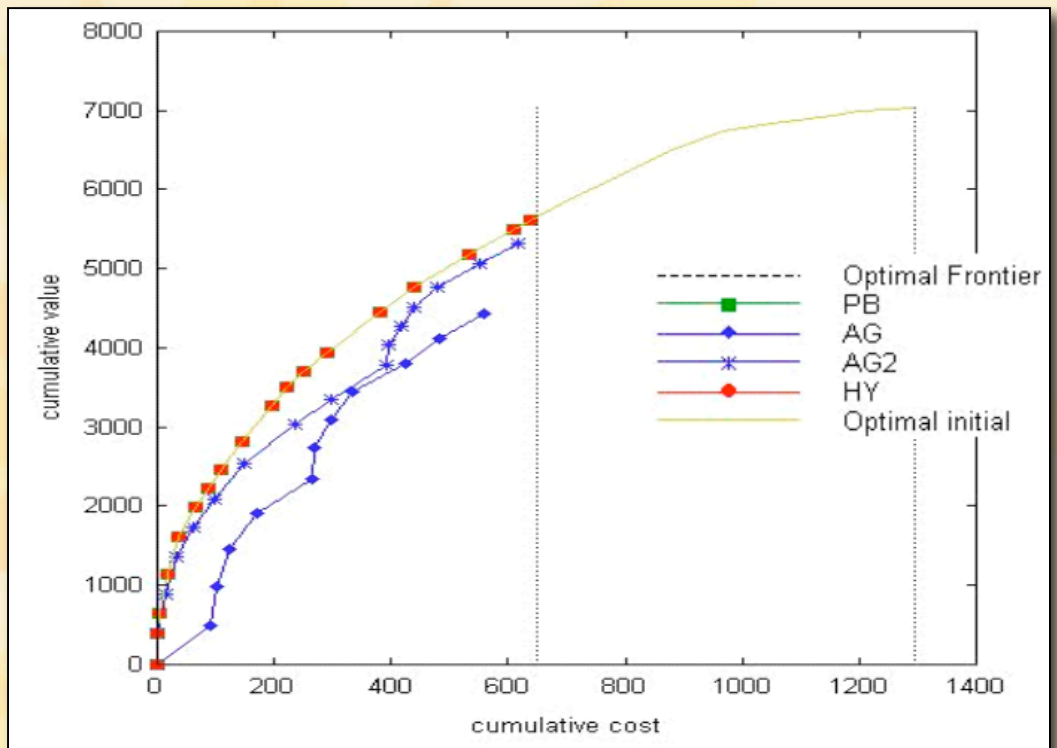
medium dynamism
 $\lambda = 1.4, \sigma = 15 \%$



- Extreme strategies (PB,AG) fail for this medium case.
- AG2 and HY perform best

One trial results (2 of 3)

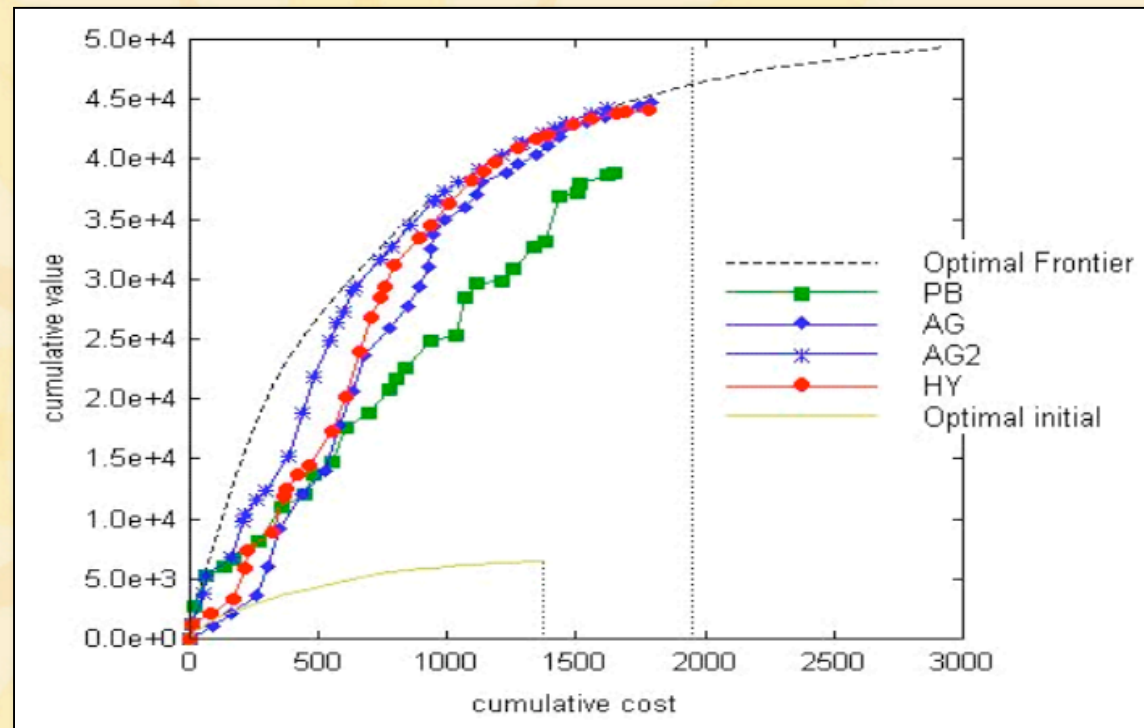
low dynamism
 $\lambda = 0.001, \sigma = 0.1 \%$



- Optimal initial = optimal frontier
- Expect: PB work best, AG worst
- Actual: HY/ PB best, both AGs worse
- And standard AG worst of all

One trial results (3 of 3)

high dynamism
 $\lambda = 20, \sigma = 200 \%$



- Expect: PB work worst, AG best
- Actual: PB worst, standard AG needs some help
- AG2 or HY beats AG

So there's more to
life than standard AG

1000 trial results

- tb = total benefits
- tc = total costs
- Ben = benefit = $tb - tc$
- CB = tb/tc
- Int = integral = area under tb/tc curve
- FR = ratio of final to the optional frontier

- HY dominates for Integral (7/9 experiments)
- PB dominates for cost (8/9 experiments)
- AG2 dominates for high λ and low to medium σ

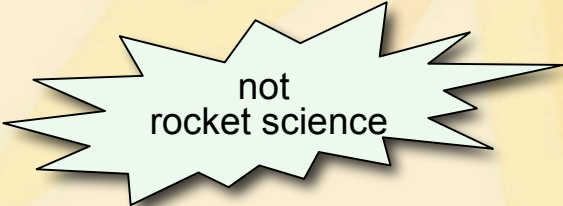
TABLE IV. AVERAGE RANKS FOR N=1000 TRIALS

HIGH $\lambda=20$	<i>Value: AG2..</i> <i>Cost: PB</i> <i>Integral: AG2</i> <i>Ben: AG2</i> <i>CB: AG2</i> <i>FR: AG2</i>	<i>Value: AG2.</i> <i>Cost: PB</i> <i>Integral: AG2</i> <i>Ben: AG2</i> <i>CB: AG2</i> <i>FR: AG2</i>	<i>Value: AG</i> <i>Cost: PB</i> <i>Integral: HY</i> <i>Ben: AG</i> <i>CB:HY, AG</i> <i>FR: HY</i>
MED $\lambda=1.4$	<i>Value: HY</i> <i>Cost: PB</i> <i>Integral: HY</i> <i>Ben: HY</i> <i>CB: HY</i> <i>FR: HY</i>	<i>Value: HY</i> <i>Cost: PB</i> <i>Integral: HY</i> <i>Ben: HY</i> <i>CB: HY</i> <i>FR: HY</i>	<i>Value: HY</i> <i>Cost: PB</i> <i>Integral: HY</i> <i>Ben: AG</i> <i>CB: HY</i> <i>FR: HY</i>
LOW $\lambda=0$	<i>Value: HY, PB</i> <i>Cost: PB</i> <i>Integral: HY</i> <i>Ben: HY, PB</i> <i>CB: PB</i> <i>FR: HY, PB</i>	<i>Value: HY</i> <i>Cost: PB, AG2</i> <i>Integral: HY</i> <i>Ben: HY</i> <i>CB: HY</i> <i>FR: HY</i>	<i>Value: HY</i> <i>Cost: HY</i> <i>Integral: HY</i> <i>Ben: HY</i> <i>CB: HY</i> <i>FR: HY</i>
	LOW $\sigma=0\%$	MED $\sigma=15\%$	HIGH $\sigma=200\%$


HY: Hybrid, PB: Plan-based, AG: Agile, AG2: Agile cost-benefit

Conclusion: Agile beats PB?

- That is the wrong question
- Better question(s)
 - What is the rate of new project requirements and value volatility?
 - What does the simulator say is the best combination of strategies for your domain?
- In these studies
 - No strong case for either PB or AG
 - (which may not hold for your next project)
- No more trite answers
 - Tune methods to local environments



not
rocket science



more studies
like this?

Challenge

- Is anyone surprised?
 - Hybrid combinations do better than the obsessive application of diametrically opposed extremes.
- How much of our time is spent debating needlessly polarized viewpoints?
 - plan vs agile
 - procedural vs object
 - model checking vs testing
 - etc
- Of course large diverse teams will combine methods
 - We should research those combinations
- More coalition
 - less opposition



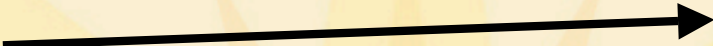


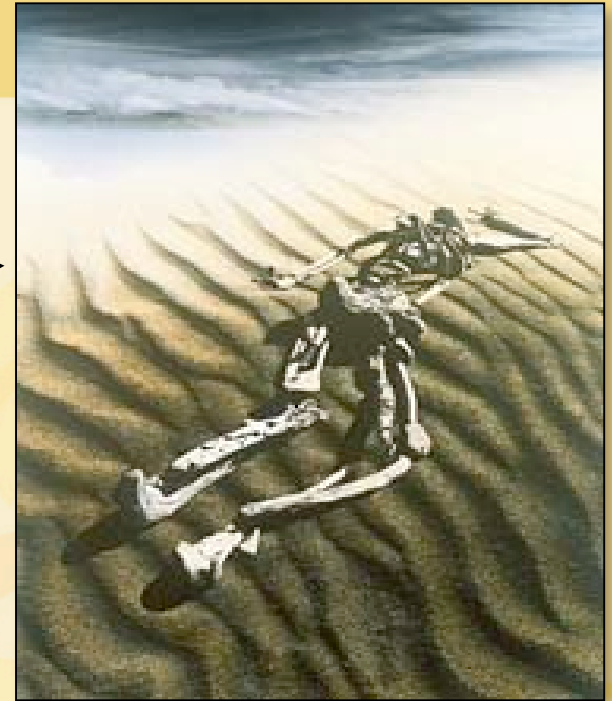
**Questions
or Comments
or ... ?**



Back up slides

Motivation

- Data drought 
 - The COCOMO data ceiling
 - (1997,2008) records = (161,161)
 - NASA's data ceiling: 2005 - 2007 (+5)
- If we can't reason fully from data,
 - Reason mostly from models
 - Informed, minimally, by current records
- This work:
 - model-based reasoning on requirements prioritization strategies
 - Study humans like atoms in a crystal
 - Stochastic, but with stable emergent properties
 - We have (just) enough data + models to report and exploit regularities in the behavior of humans developers.
- Main result:
 - new prioritization halfway between two polarized positions
 - Not “agile is best”
 - Not “pre-planning is best”
 - But a new hybrid strategy



The “Separation of Concerns” legacy

- “The notion of ‘user’ cannot be precisely defined, and therefore has no place in CS or SE.”
 - Edsger Dijkstra, ICSE 4, 1979
- “Analysis and allocation of the system requirements is not the responsibility of SE, but a prerequisite for their work.”
 - Mark Paulkat al., SEI Software CMM v.1.1, 1993
- Now, after decades of SE...
 - No more separation?
 - Study humans like atoms in a crystal
 - Stochastic, but with stable emergent properties
 - We have (just) enough data + models to report and exploit regularities in the behavior of humans developers.

Cao, L., Ramesh, B.,
Requirements Engineering
Practices: An Empirical Study,
IEEE Software,
Vol 25, p60- 67, 2008
• Data from 16 companies